

**MICROGRAVITY ACCELERATION MEASUREMENT
AND ENVIRONMENT CHARACTERIZATION SCIENCE
(17-IML-1)**

Science

The Space Acceleration Measurement System (SAMS) is a general purpose instrumentation system designed to measure the accelerations onboard the Shuttle Orbiter and Shuttle/Spacelab vehicles (see Figure 1). These measurements are used to support microgravity experiments and investigations into the microgravity environment of the vehicle. Acceleration measurements can be made at locations remote from the SAMS main instrumentation unit by the use of up to three remote triaxial sensor heads. The SAMS was developed by NASA's Lewis Research Center (LeRC) in support of NASA's microgravity science programs.

The prime objective for SAMS on the IML-1 mission will be to measure the accelerations experienced by the Fluid Experiment System (FES). The SAMS acceleration measurements for FES will be complemented by low-level, low-frequency acceleration measurements made by the Orbital Acceleration Research Experiment (OARE) installed on the shuttle. Secondary objectives for SAMS will be to measure accelerations at several specific locations to enable the acceleration transfer function of the Spacelab module to be analyzed. This analysis effort will be in conjunction with similar measurements analyses on other Spacelab missions.

In the past, numerous acceleration measurement systems have flown on various space missions. These systems were tailored to measure accelerations for a narrow set of requirements and were limited in bandwidth, dynamic range, and recording capability. In addition, these systems were mission peculiar and not easily modified for other applications. The result has been an inability to accurately assess the expected microgravity environment prior to a mission for a particular experiment and/or location.

SAMS configurations are under development for the Orbiter Middeck locker area, Spacelab SMIDEX rack and Spacelab center aisle and under development for the Orbiter cargo bay, enabling microgravity measurements at nearly any desired payload location.

SAMS units are currently manifested on the SLS-1, IML-1, SL- J, USML-1, USMP-1 and IML-2 missions. There will be eight flight units fabricated to support the expected flight rate of microgravity science missions (e.g., IML-3, USML-2, USMP-2).

Instrument

A SAMS unit consists of a main unit (shown in Figure 2 with one triaxial sensor head) and up to three remote triaxial sensor heads. The main unit is comprised of the crew interface, optical disk data storage devices, and control and processing electronics. The remote triaxial

sensor heads are comprised of three single axis acceleration sensors, preamplifiers and filters. Each head is connected to the main unit by an umbilical cable which has a maximum length of 20 feet.

The low-pass bandwidth for a triaxial sensor head is independent of the bandwidth of the other two heads and is chosen to match the requirements of the supported experiment. Standard choices for the low-pass bandwidth of a head are 0 to 2.5, 5, 10, 25, 50, and 100 Hz.

The standard SAMS triaxial sensor head employs the Sundstrand QA-2000 sensors, having a resolution of 1 μ g. Two triaxial sensor heads utilizing Bell XI-79 sensors are also available having a resolution of 0.01 μ g. The SAMS uses simultaneous sample and hold circuits to maintain phase coherence in the three axis measurements of a given triaxial sensor head. Similarly, the outputs of the three sensors of a given triaxial sensor head are digitized by the same 16 bit analog to digital converter. The signal processing for each triaxial sensor head has filtering characteristics matched to the data sampling rate for that triaxial sensor head. The preamplifier has four decade gain ranges and the capability for an electronic calibration mode.

The triaxial sensor head digitized data is formatted and transferred to optical disk. The optical disk drive enables crew-tended disk changes which allow nearly unlimited data storage during a mission. With 200 megabytes of storage per optical disk side, typical times between disk change operations are from hours to days, depending on the triaxial sensor head sampling rates.

To support the FES on IML-1, one SAMS head will be mounted on the FES optical bench in rack #10. This triaxial sensor head will utilize Sundstrand model QA1000 sensors and will be set for 100 hertz and 500 samples per second. This will result in measuring the acceleration environment experienced by the equipment mounted on the FES optical bench.

To measure the low-frequency accelerations experienced by the FES, the second head will be mounted toward the bottom of rack #10 and will be set for 2.5 hertz and 12.5 samples per second. This triaxial sensor head will utilize more sensitive Bell model XI-79 sensors and will be set for 2.5 hertz and 12.5 samples per second. Acceleration data (below 1 hertz) from the OARE will also be utilized to complement these low-frequency SAMS measurements. The OARE utilizes a MESA type of sensor which is particularly good (although expensive) for low-frequency, low magnitude measurements.

The third SAMS head will be mounted below the Spacelab module floor beneath the Microgravity Vestibular Investigations (MVI) rotating chair. This triaxial sensor head will utilize Sundstrand model QA2000 sensors and will be set for 100 hertz and 500 samples per second. This will characterize the MVI rotating chair as an acceleration source and will, in conjunction with the other two heads, allow characterization of the Spacelab module acceleration transfer function to be studied.

Data Processing and Analysis

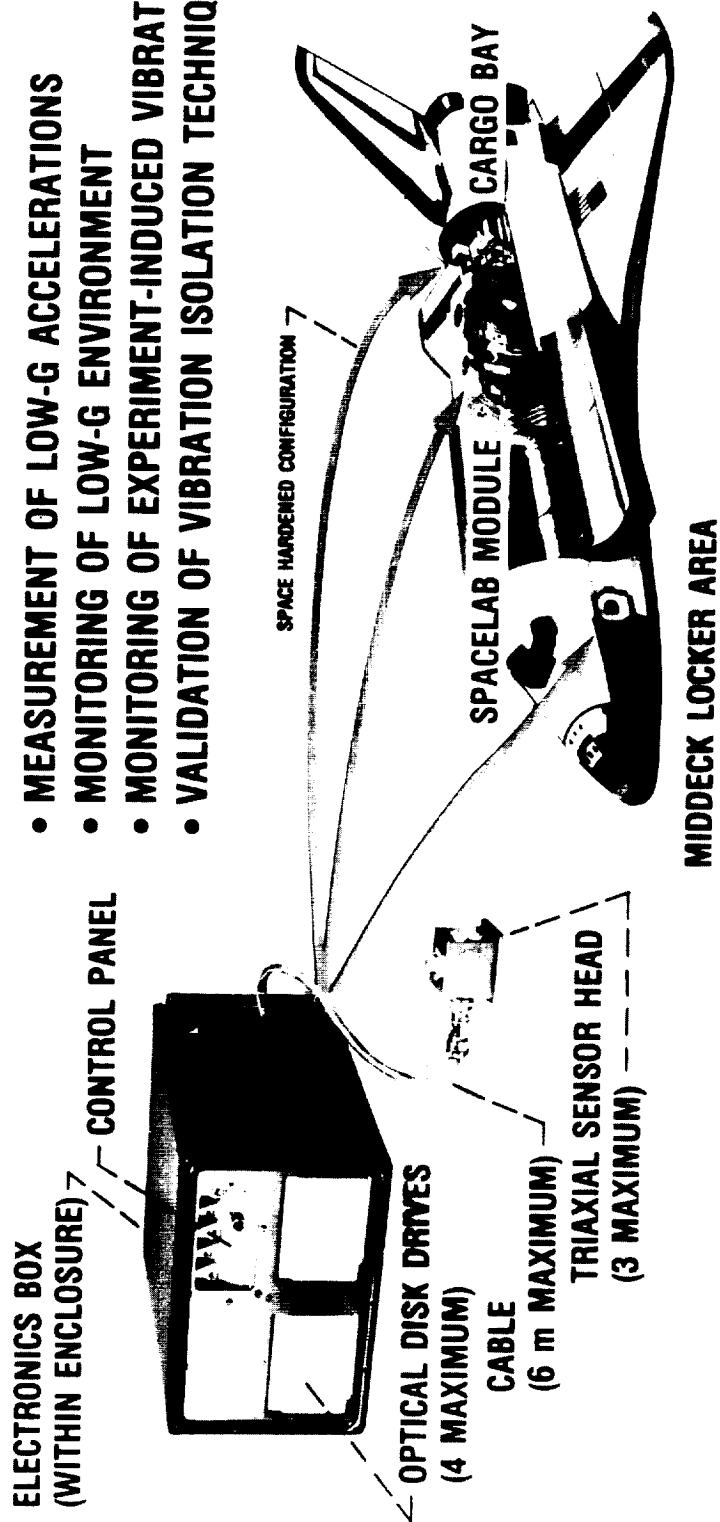
Post mission processing of data by the SAMS project will be limited to data extraction, compensation, identification, format conversion, archival and dissemination. The processed data will be provided to the principal investigators involved with the particular mission and other interested organizations as required.

In conjunction with the SAMS project, researchers at The University of Alabama at Huntsville and The Charles Stark Draper Laboratories have initiated work to characterize the microgravity environment using the data obtained from the Spacelab-3 mission and the IML-1 mission.

The archival of SAMS data, combined with acceleration data from other sources (e.g., OARE, experiment accelerometers) will make possible the assessment of the microgravity environment of the Shuttle and Spacelab vehicles. This is an important step towards accommodating science experiments on these vehicles.

APPLICATIONS OF THE SAMS

- MEASUREMENT OF LOW-G ACCELERATIONS
- MONITORING OF LOW-G ENVIRONMENT
- MONITORING OF EXPERIMENT-INDUCED VIBRATIONS
- VALIDATION OF VIBRATION ISOLATION TECHNIQUES



TYPICAL LOCATIONS FOR THE SAMS

Figure 1. Space acceleration measurement system (SAMS).

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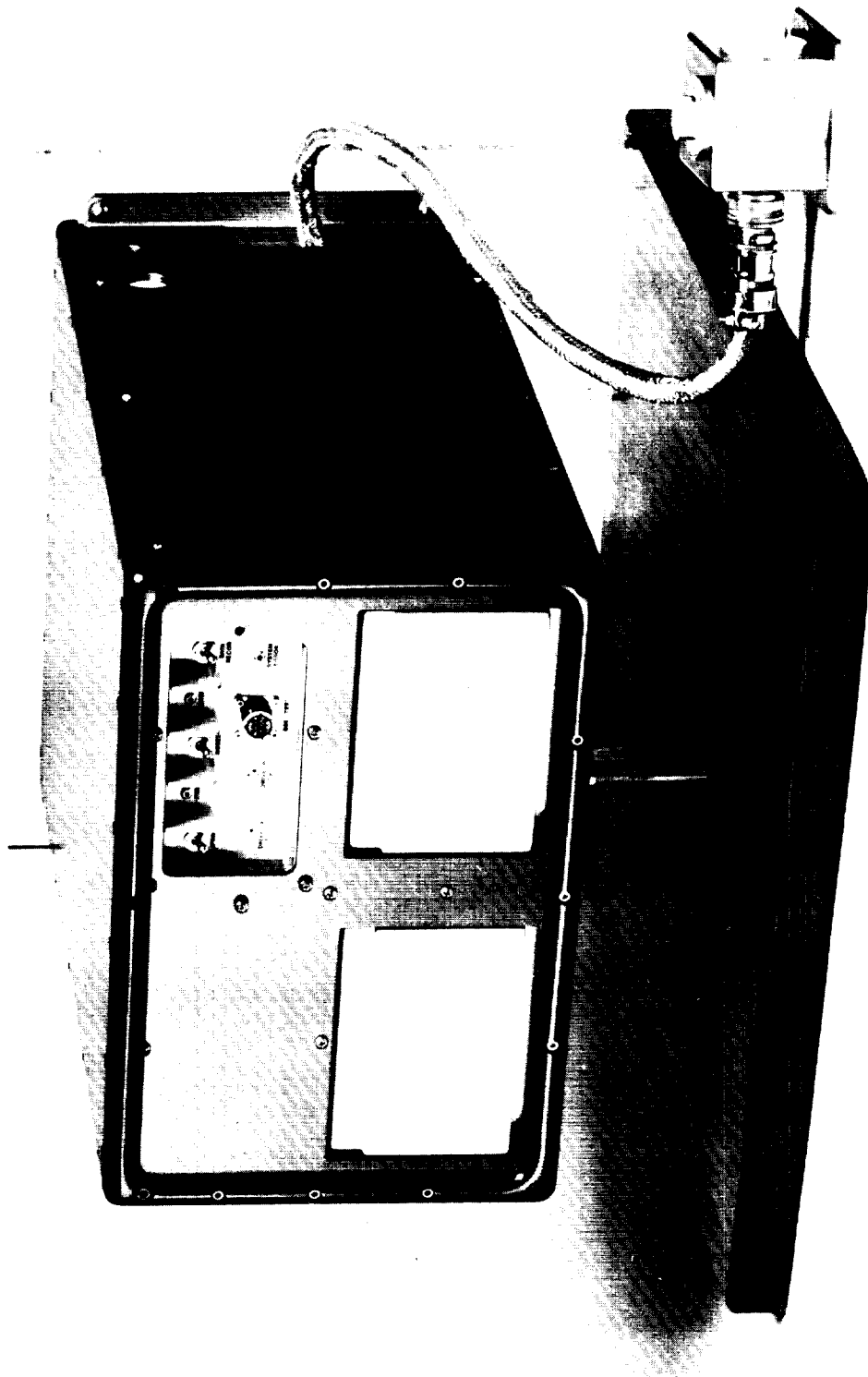


Figure 2. SAMS main unit with one triaxial sensor head.

APPENDIX

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INTERNATIONAL MICROGRAVITY LABORATORY 1 CO-INVESTIGATORS
AND GUEST INVESTIGATORS

Life Sciences

Gravitropic Responses of Plants in the Absence of a Complicating G-Force (6-IML-1)

A. Johnson
University of Trondheim
Norway

D. Heathcote
D. Chapman
Gravitational Plant Physiology Laboratory
USA

A Spaceflight Experiment to Investigate the Effects of a Range of Unilateral Blue Light Stimulations on the Movements of Wheat Coleoptiles (6-IML-1)

A. Brown
D. Chapman
Gravitational Plant Physiology Laboratory
USA

Genetic and Molecular Dosimetry of HZE Radiation (7-IML-1)

E. Benton
University of San Francisco
USA

Chondrogenesis in Micromass Cultures of Embryonic Mouse Limb Mesenchymal Cells Exposed to Microgravity (7-IML-1)

T. Hewitt
The Johns Hopkins University and Hospitals
USA

Microgravitational Effects on Chromosome Behavior (7-IML-1)

J. Colasanti
East Carolina University School of Medicine
USA

Effects of Microgravity and Mechanical Stimulation on the In Vitro Mineralization and Resorption of Fetal Mouse Long Bones (7-IML-1)

E. Burger
G. Kampen
ACTA Gree University de Boelelaan
The Netherlands

The Role of Gravity in the Establishment of the Dorsoventral Axis in the Amphibian Embryo (7-IML-1)

Effect of the Space Environment on the Development of Drosophila Melanogaster (7-IML-1)

T. Gonzalez-Jurado
M. Maroto
UAM Institute of Biomedical Investigations
Spain

The Effect of Microgravity Environment on Cell Wall Generation, Cell Division, Growth and Differentiation of Plants From Protoplasts (7-IML-1)

T. Iverson
University of Trondheim
Norway

R. Wyndaele
J. Christiansen
Institute of Molecular Biology and Plant Physiology
Denmark

Embryogenesis and Organogenesis of Carausius Morosus Under Spaceflight Conditions (7-IML-1)

R. Facius
G. Reitz
Institute of Aerospace Medicine, DLR
Federal Republic of Germany

R. Beaujean
W. Enge
University of Kiel
Federal Republic of Germany

W. Heinrids
GH University of Siegen Adolf Reichwein
Federal Republic of Germany

E. Graul
W. Ruther
University of Marburg
Federal Republic of Germany

Dosimetric Mapping Inside Biorack (7-IML-1)

H. Buecker
R. Facius
M. Schaefer
DLR
Federal Republic of Germany

R. Beaujean
W. Enge
Universitat Kiel
Federal Republic of Germany

W. Heinrich
Universitat of Siegen
Federal Republic of Germany

Growth and Sporulation in Bacillus Subtilis Under Microgravity (7-IML-1)

M. Lange
B. Ernst
University of Frankfurt
Federal Republic of Germany

Friend Leukemia Virus Transformed Cells Exposed to Microgravity in the Presence of DMSO (7-IML-1)

O. Meuller
University of Berne
Switzerland

P. Bechler
M. Cogoli
Institut for Biotechnologie
Switzerland

Proliferation and Performance of Hybridoma Cells in Microgravity (7-IML-1)

P. Bechler
M. Cogoli
Institut for Biotechnologie
Switzerland

Dynamic Cell Culture (7-IML-1)

C. Nordau
University of Paris
France

F. Gmuender
Institut for Biotechnologie
Switzerland

The Genotypic Control of Graviresponse, Cell Polarity and Morphological Development of Arabidopsis Thaliana in a Microgravity Environment (7-IML-1)

Transmission of Gravistimulus in the Statocyte of the Lentil Root (7-IML-1)

D. Driss-Ecole
G. Salle
Pierre and Marie Curie University
France

K. Waldon
University of Glasglow
United Kingdom

Gravity Related Behavior of the Acellular Slime Mold Physarum Polycephalum (7-IML-1)

W. Briegleb
DLR
Federal Republic of Germany

K. Wohlfarth-Bottermann
University of Bonn
Federal Republic of Germany

Studies of Penetration of Antibiotics in Bacterial Cells in Space Conditions (7-IML-1)

N. Moatti
L. Lapchine
G. Richoilley
J. Templier
J. Bes
G. Gasset
G. Farre
B. Eche
National Institute of Health and Medical Research
France

Energy Expenditure in Space Flight (8-IML-1)

M. Preshaw
H. Krouse
University of Calgary
Canada

J. Thirsk
Foothills Hospital, Calgary
Canada

Back Pain in Astronauts (8-IML-1)

R. Gagnon
L. Susak
F. Gagnon
I. Tsang
University of British Columbia
University Hospital (Shaughnessy Site)
Canada

Measurement of Change in Venous Compliance in Microgravity and Evaluation of an
Experimental Antigravity Suit (8-IML-1)

L. Goodman
M Pecaric
K. Ackles
Defence and Civil Institute of Environmental Medicine
Canada

J. Bennett
J. Charles
Lyndon B. Johnson Space Center
USA

R. Aaslid
University of Berne, Inselspital
Switzerland

M. Kassam
P. Dunphy
Ryerson Polytechnical Institute
Canada

D. Leiski
P. Sullivan
R. Bondar
Canadian Space Agency
Canada

Space Adaptation Syndrome Experiments (8-IML-1)

G. Melville Jones
McGill University
Canada

J. Lackner
Brandeis University
USA

J. Landolt
Defense and Civil Institute of Environmental Medicine
Canada

M. Reschke
Lyndon B. Johnson Space Center
USA

L. Young
Massachusetts Institute of Technology
USA

A. Bensen
RAF Institute of Aviation Medicine
United Kingdom

F. Guedry
Naval Aerospace Medical Research Laboratory
USA

R. Jell
University of Manitoba
Canada

D. Parker
Miami University
USA

Phase Partitioning Experiment (8-IML-1)

J. Van Alstine
J. Harris
University of Alabama in Huntsville
USA

J. Boyce
University of British Columbia
Canada

Microgravity Vestibular Experiments (10-IML-1)

D. Anderson
University of Michigan
USA

A. Berthoz
CNRS
France

O. Black
Good Samaritan Hospital
USA

G. Clement
CNRS
France

B. Cohen
Mount Sinai Medical Center
USA

F. Guedry
Naval Aerospace Medical Research Laboratory
USA

J. Homick
Lyndon B. Johnson Space Center
USA

M. Igarashi
Baylor College of Medicine
USA

P. Dizio
R. Lackner
Brandeis University
USA

C. Oman
Massachusetts Institute of Technology
USA

D. Parker
Miami University of Ohio
USA

J. Vanderploeg
S. Wood
W. Poloski
KRUG International
USA

A. Benson
RAF Institute of Aviation Medicine
United Kingdom

R. Jell
University of Manitoba
Canada

D. Watt
McGill University
Canada

T. Raphan
O. Garriott
Teledyne Brown Engineering
USA

Biostack (14-IML-1)

R. Beaujean
W. Enge
Universitat Kiel
Federal Republic of Germany

E. Benton
University of San Francisco
USA

A. Kranz
U. Bork
Universitat Frankfurt
Federal Republic of Germany

R. Facius
G. Horneck
G. Reitz
M. Schaefer
J. Schott
DLR
Federal Republic of Germany

W. Ruether
O. Gaul
Universitat Marburg
Federal Republic of Germany

W. Heinrich
Universitat Marburg
Federal Republic of Germany

J. Keifer
Strahlenzentrum
Federal Republic of Germany

A. Tallentire
University of Manchester
United Kingdom

S. Takaski
Japan Atomic Energy Research Institute
Japan

F. Masami
Institute of Space and Aeronautic Sciences
Japan

I. Ken-Ichic
University of Tokyo
Japan

T. Hirsohi
National Cancer Research Center
Japan

Mental Workload and Performance Evaluation (15-IML-1)

B. Lichtenberg
Payload Systems, Inc.
USA

Radiation Monitoring Container/Dosimeter (16-IML-1)

T. Doke
Waseda University
Japan

T. Takahashi
Institute for Physical and Chemical Research
Japan

T. Iwasaki
Science and Technology Agency
Japan

K. Ogura
Nihon University
Japan

Y. Ishikawa
Tokyo University of Fisheries
Japan

M. Ikenaga
Institute of Radiation Biology
Japan

H. Watanabe
Japan Atomic Energy Research Institute
Japan

Microgravity Sciences

Study of Solution Crystal Growth in Low Gravity (2-IML-1)

W. Wilcox
Clarkson University
USA

J. Trolinger
Metrolaser
USA

A. Batra
Alabama A & M University
USA

Studying the Influence of Gravity on Fluid Flow and Nucleation During Casting Through Directional Solidification of a Transparent Metal Model Under Microgravity Conditions (2-IML-1)

L. Smith
T. McCay
S. Lowry
J. Hopkins
M. Vesko
University of Tennessee
USA

R. Porter
George C. Marshall Space Flight Center
USA

Vapor Crystal Growth Studies of Single Mercuric Iodide Crystals (3-IML-1)

C. Baccash
L. Frank
EG & G/EM, Inc.
USA

Mercury Iodide Nucleation and Crystal Growth in Vapor Phase (4-IML-1)

G. Le Lay
CNRS
Marseille, France

L. Van den Berg
EG & G/EM, Inc.
USA

Protein Crystal Growth (5-IML-1)

Y. Babu
BioCryst Limited
USA

R. Naumann
E. Meehan
J. Baird
University of Alabama in Huntsville
USA

G. Birnbaum
National Research Council of Canada
Canada

C. Carter, Jr.
University of North Carolina
USA

D. Carter
R. Snyder
George C. Marshall Space Flight Center
USA

W. Rosenblum
L. DeLucas
S. Ealick
V. Senadhi
W. Cook
The University of Alabama at Birmingham
USA

E. Czerwinski
University of Texas Medical Branch
USA

D. Duchamp
H. Einspahr
B. Finzel
K. Watenpaugh
The Upjohn Company
USA

D. Eggleston
Smith Kline & French
USA

J. Camps
Laboratoire de Cristallographie et Cristallisation de
Macromolles Biologiques
France

N. Jones
Eli Lilly & Company
USA

T. Krenitsky
Burroughs-Wellcome Company
USA

W. Laver
The Australian Nation University
Australia

D. Voet
P. Lu
University of Pennsylvania
USA

A. McPherson
University of California at Riverside
USA

E. Meyer
Texas A & M University
USA

P. Trotta
T. Nagabhushan
Schering Corporation
USA

M. Navia
Merck, Sharpe & Dohme Research Labs
USA

W. Riley
The Dow-Elanco, Central Research, Biotechnology Labs
USA

M. Ross
Genentech, Inc.
USA

B. Rubin
Eastman Kodak Company
USA

F. Salemme
P. Weber
DuPont de Nemours and Company
USA

R. Sweet
B. Schoenborn
Brookhaven National Laboratory
USA

L. Sieker
University of Washington
USA

P. Sigler
Yale University
USA

F. Suddath
Georgia Institute of Technology
USA

K. Ward
Naval Research Laboratory
USA

A. Yonath
The Weizmann Institute of Science
Israel

Organic Crystal Growth with G-Jitter Preventative Measures (13-IML-1)

H. Anzai
M. Tokumoto
M. Keizo
K. Nobumori
Electrotechnical Laboratory
Japan

S. Yoda
National Space Development Agency of Japan
Japan

H. Kazumasa
Institute of Chemistry, NITTI
Japan

I. Kurihide
Kyoto University
Japan

Cryostat (18-IML-1)

Critical Point Facility (19-IML-1)

P. Guenoun
F. Perrot
Service de Physique de l'Etat Condense`
CE Saclay
France

Y. Garrabos
B. Le Neindre
CNRS
France

R. Berg
M. Moldover
NIST
USA

R. Gammon
University of Maryland
USA

J. Straub
Tech. University Muennechan
Germany

H. van den Berg
C. Prins
B. van Deenen
H. Sa Konidou
T. van Lieshont
University of Amsterdam
The Netherlands

IMAX (12-IML-1)

Space Acceleration Measurement System (17-IML-1)

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